

Fundamental Anylogic Classes

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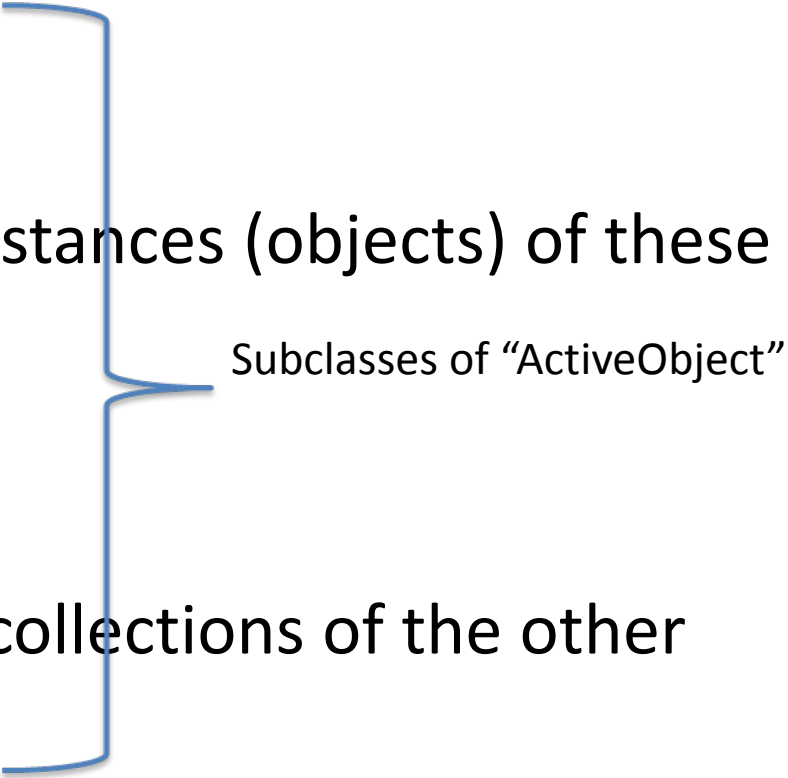
Object-Oriented Programming Lingo...

- A software “object” is an entity that is associated with
 - Some State
 - Some behaviour
- A software “class” describes a whole category of behaviourally similar objects
 - This is like the “mould” that is used to make the objects
 - While objects associated with this class may differ in the details of their state, they have behavioural similarities
 - We say that objects represented by this class are “instances of the class”

Classes: Design & Run Time Elements

- The AnyLogic interface makes critical use of a hierarchy of *classes* (e.g. *Main*, *Agent* classes, *Experiment* classes)
 - These classes each represent the properties & behaviour of one or more particular objects at runtime
 - We will be discussing this hierarchy more in a later session
- Each of these classes is associated with both
 - Design time interface (appearance at design time)
 - Run time elements (presence of the class object and instances of the class at runtime)

Key Customized Classes

- The structure of the model is composed of certain key user-customized “classes”
 - “Agent” classes
 - Your agent classes
 - There are typically many instances (objects) of these classes
 - “Main” class
 - Normally just one instance
 - This will generally contain collections of the other classes
 - “Experiment” classes
 - These describe assumptions to use when running the model
- 
- Subclasses of “ActiveObject”

Relationship Between Key Classes

- The Main object normally contains one or more populations of “replicated” agents
 - Each population consists of agents of a certain class (or a subclass therefore) (e.g. “Hares”)
 - The Main object might contain more than one population (e.g. “Hares”, “Lynxes”)
- Agent objects are normally embedded within the (single) Main object
 - Need to mark these as Agents by checking the “Agent” checkbox in their properties

Agent Populations

- Within the Main class, you can create representations of subpopulations by dragging from an Agent class into the Main class area
- Through the “Replication” property, the number of these agents can be set
- The “Environment” property can be used to associated the agents with some surrounding context (e.g. Network, embedding in some continuous space, with a neighborhood)
- Statistics can be computed on these agents

Multiple Agent Classes

- Frequently we will seek to have multiple types of agents, each with differing types of behavior
- Sometimes these agents – while interacting – will have radically different factors that affect them
 - Cf “PredatorPrey” model, with Lynx & Hare
- Sometimes these agents – while distinctive – will be closely related in many ways
 - Here, we may wish to accomplish this through *subclasses of some common custom agent “superclass”*
 - The common features of the agents would be captured in the superclass

Capturing Agent Heterogeneity:

When To Parameterize vs. Use Distinct Classes

- We can capture heterogeneity in agent populations both via using distinct classes (e.g. via subclassing) and via parameterization
- Distinct classes are advisable when there are fundamental behavioural differences
 - The roles that govern the changes in behavior are different
 - There are differences in the types of *behaviour* that the agents can take on
- Use differences in parameterization if the agents are governed by similar rules, but different in their situation/details of context within the rules

Embedded Objects

- The primary AnyLogic customized classes (Main & Agent classes) contain certain elements
 - Parameters
 - Variables
 - “Actions”
 - Elements of presentations

Design Time Components

- Properties for entities
 - Values to use at runtime/Bits of code/Data types/Initial values of state variables/parameter values
- Declaring & manipulating variables, parameters, functions, etc.
- Prepare for runtime using “build”
 - If all goes well, this translates project to executable Java
 - This may alert you to errors in the project
- Define the visual elements to use for each agent
- In an agent-based model, we have only one class for each *type* of object (e.g. “Person”, “Doctor”)

Parameters: Static Quantities

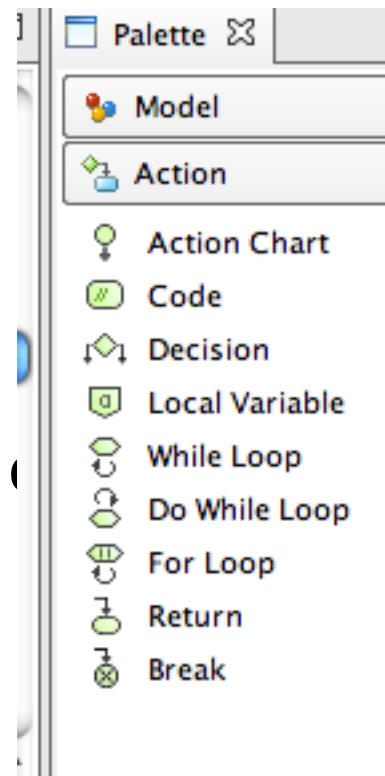
- Parameters normally define constants that represent assumptions
- In Java, such parameters can have many types
 - Integer, Double precision value, boolean, etc.
- For parameters in the *Main* class, we can override the value of the parameters in an experiment
- Presentation elements associated with an Agent have special “Presentation” tab for their parameters

Variables: Dynamic Quantities

- Variables are used for time-varying quantities
- Note that some variables (e.g. stocks) are defined using other “primitive” objects directly supported by AnyLogic
- As for parameters, variables come with many types
- If we want to create an instance variable with a particular class, we should do it with a variable
 - Declaring things using variables (rather than in code) gives us the option of browsing these things at runtime

Expressing Algorithms

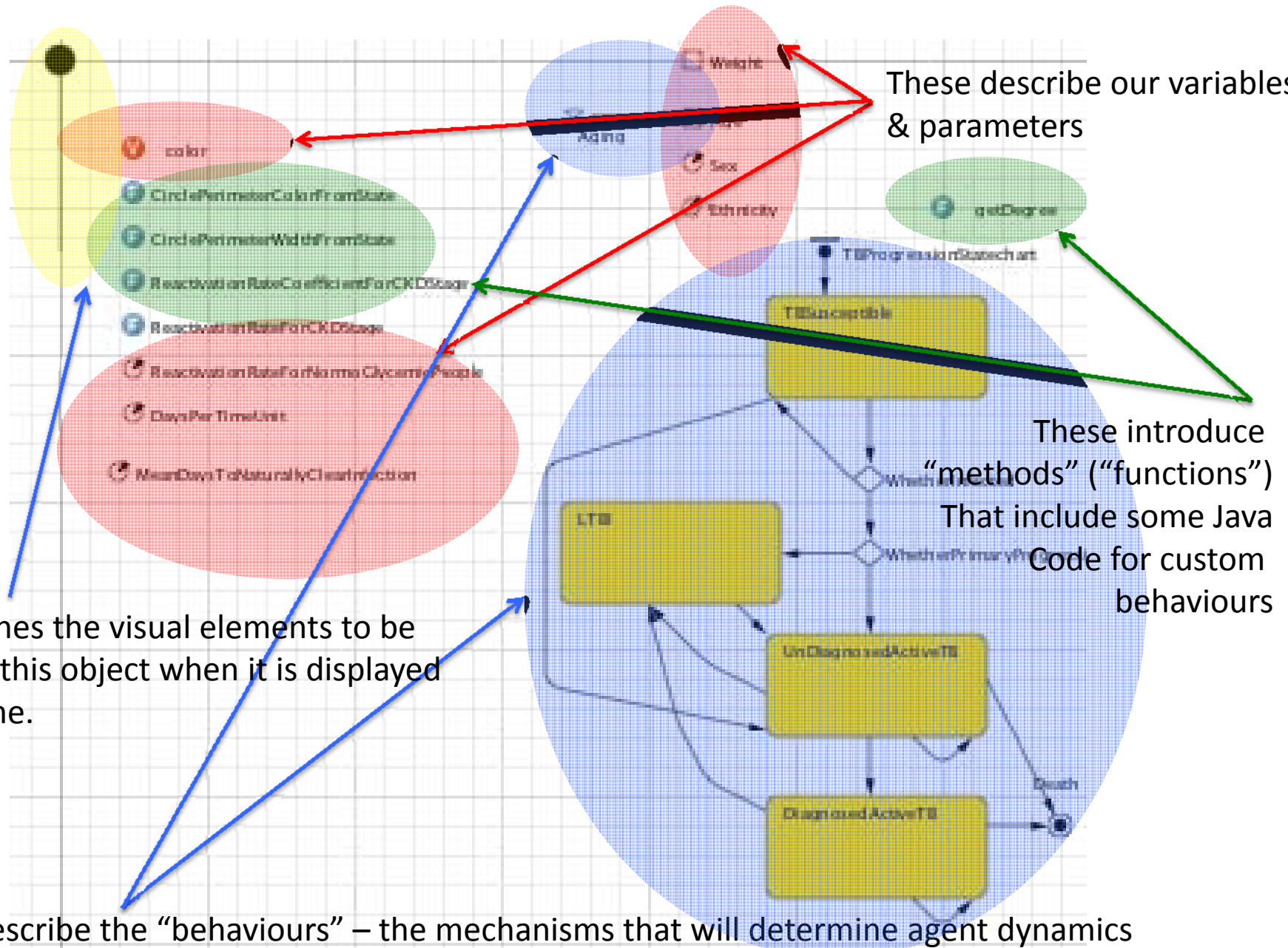
- Algorithms in AnyLogic may be expressed in two ways
 - Defining functions (here, the modeler is responsible for writing the Java code for the function)
- Using the “Action” elements
 - This defines a function primarily graphically
 - Element require filling in pieces (e.g. the expression by which to decide the condition, the variables over which to loop)
 - Custom code can be inserted where desired



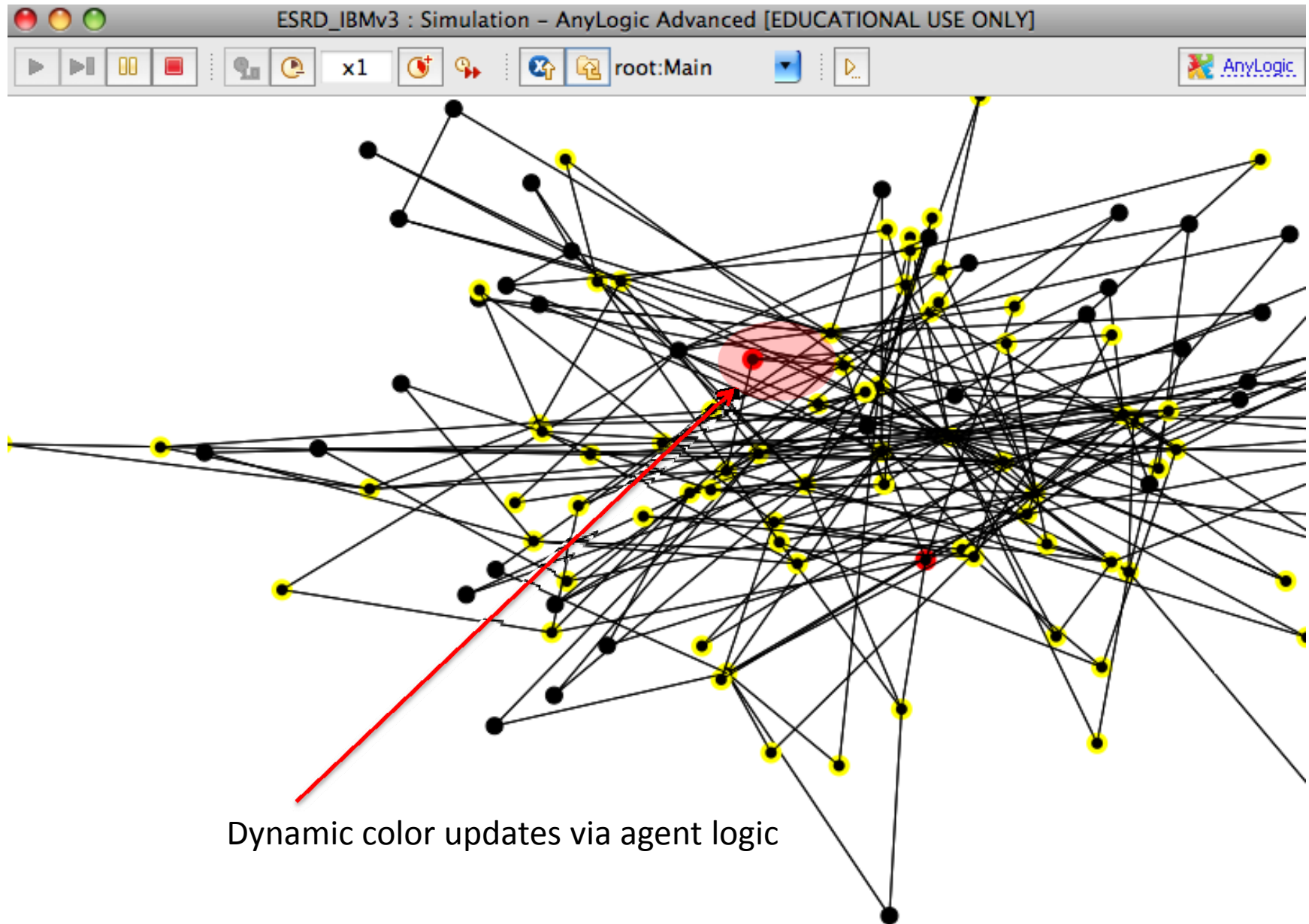
Execution Time

- Here, the simulation is running
- Time is running along
- Each agent class will typically have many particular agents in existence
 - Each agent will have a particular state
 - This population may fluctuate
- Variables will be changing value
- Presentation elements will be knit together into a dynamic presentation

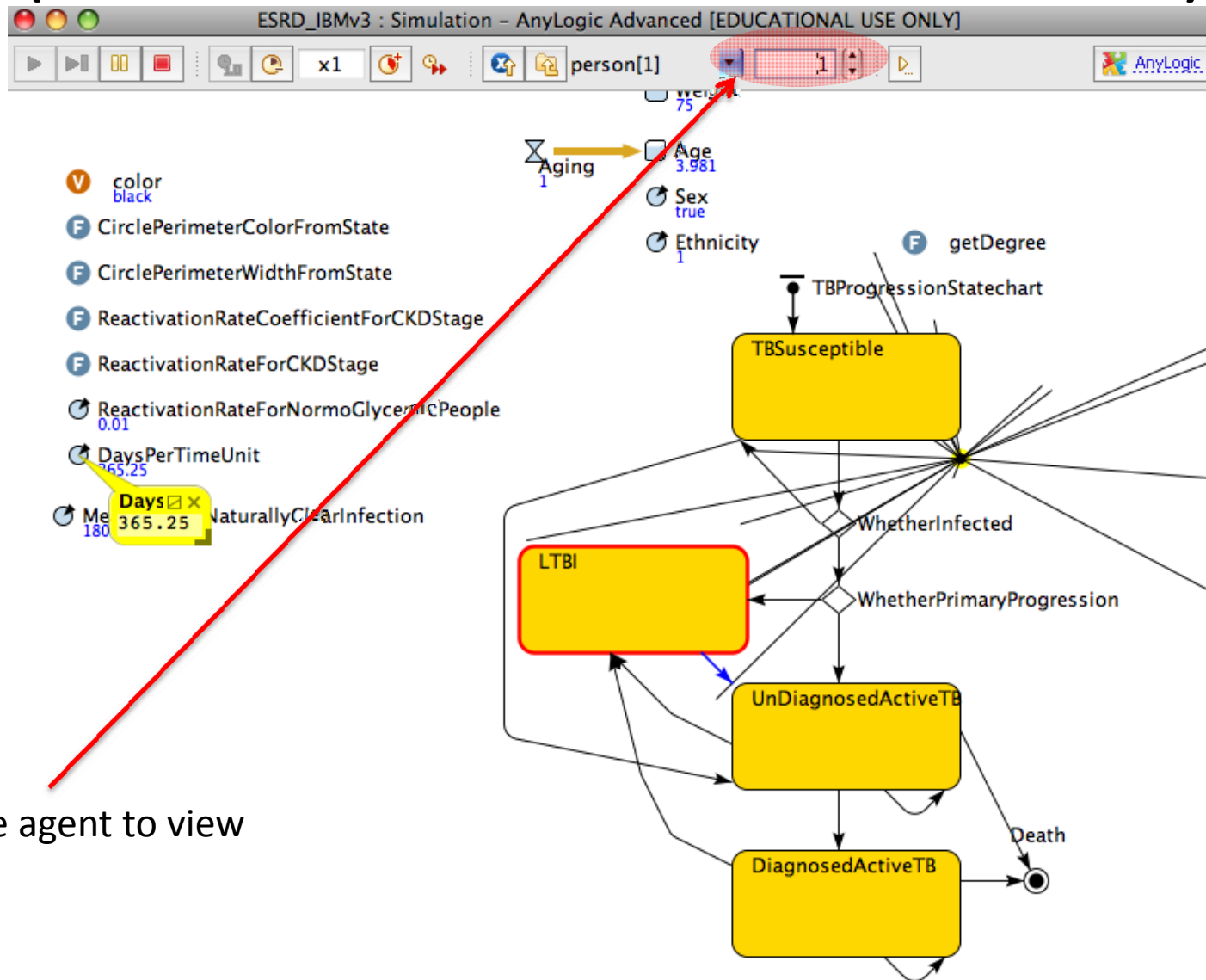
Example Design Time View



Network Embedding of Agents



Runtime View of Particular Agent (Drill Down from Previous View)



Selects the agent to view

Experiment Classes

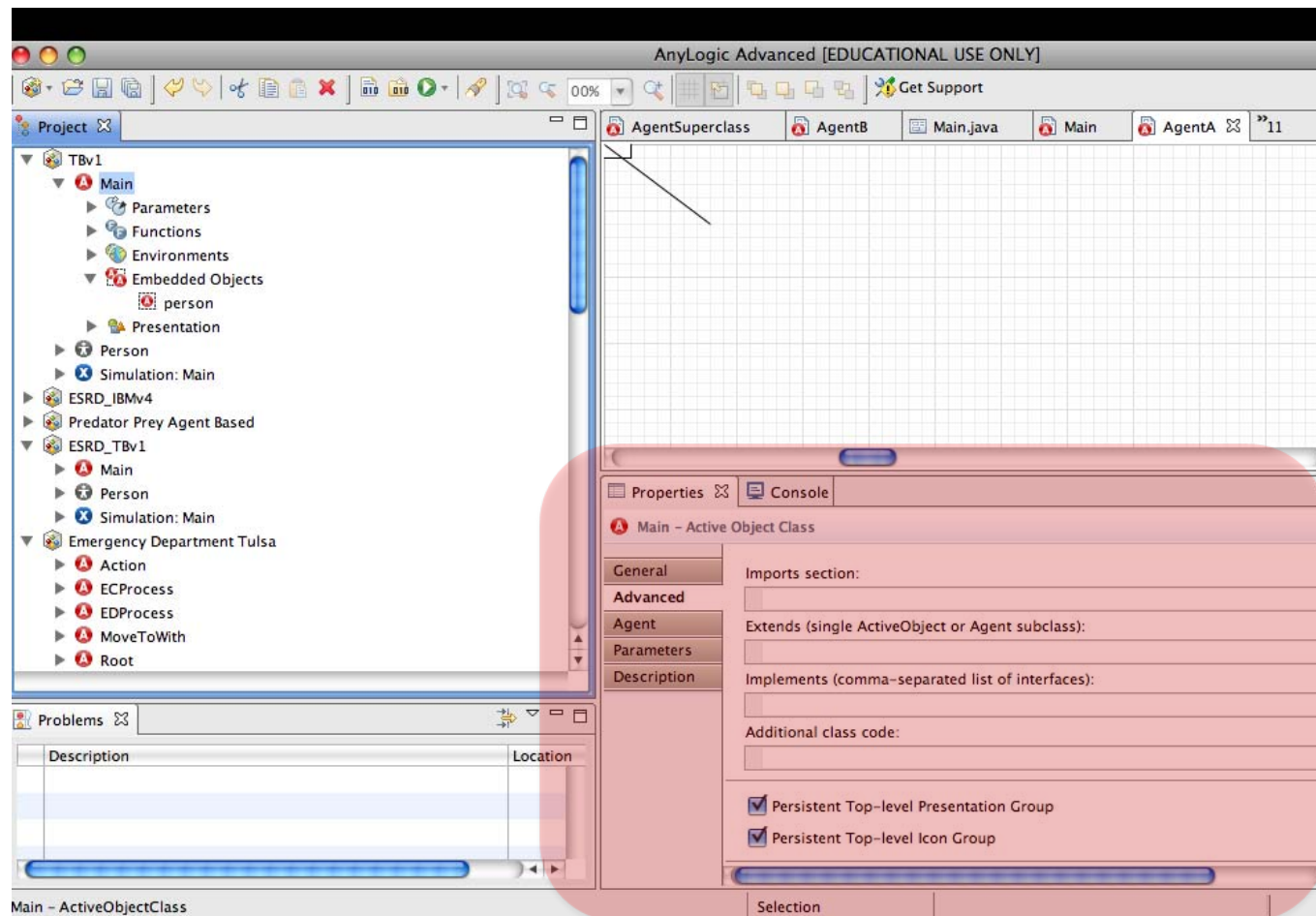
- Experiment classes allow you to define & run scenarios in which global parameters (i.e. parameters defined in *Main*) may hold either default or alternative values
- Experiment classes are also used to set
 - The time horizon for a simulation
 - Memory limits (important for large models)
 - Details of simulation run
 - Details on random number generation
- “Properties” allow one to set the values for each parameter
- Right click on these & choose “Run” to run such a scenario

Java Code: When & How Much?

- AnyLogic offers lots of ways to insert snippets (“hooks”) of Java code
- You will need these if you want to e.g.
 - Push AnyLogic outside the envelop of its typical support
 - e.g. Enabling a network with diverse Agent types
 - Send messages
 - Put into place particular initialization mechanisms
 - Collect custom statistics over the population

Examples of Where to Insert Code Object Properties

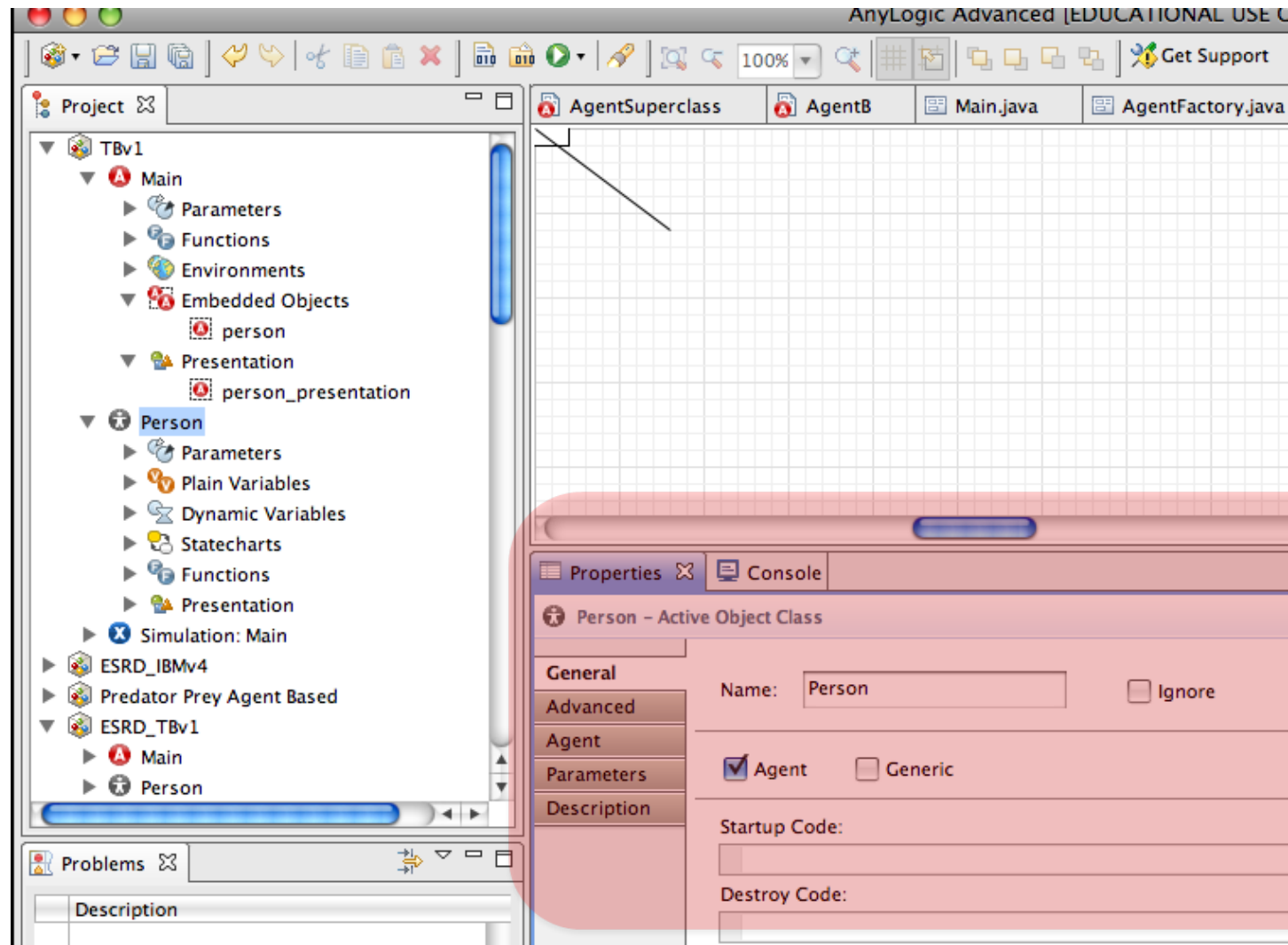
- “Advanced”



Examples of Where to Insert Code

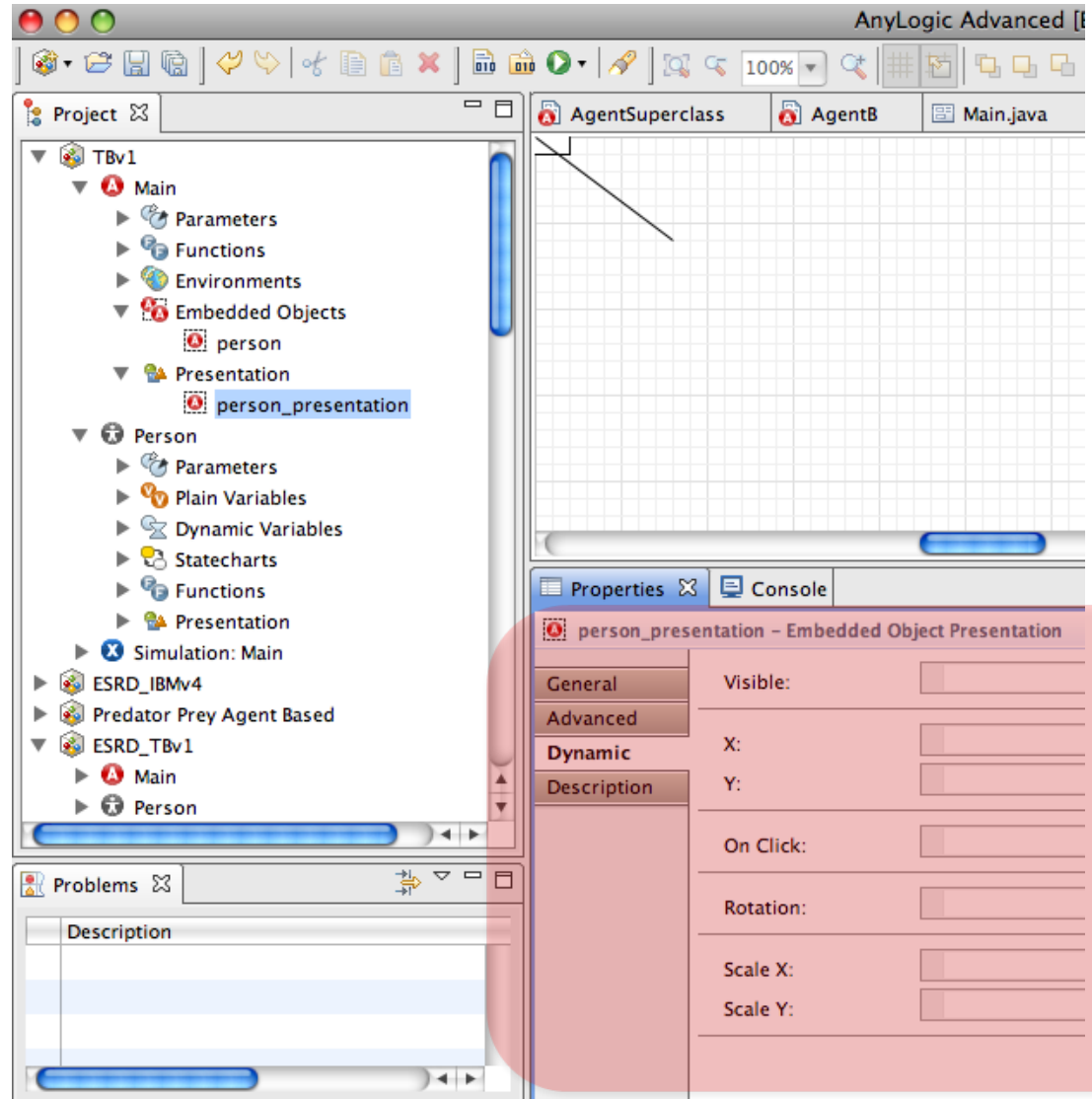
Object Properties

- “General”



Examples of Where to Insert Code Presentations Properties

- “Dynamic”



Finding the Enclosing “Main” class from an Embedded Agent

- From within an embedded Agent, one can find the enclosing “Main” class by calling `get_Main()`
 - This will give a reference to the single instance (object) of the Main class in which the agent is embedded
 - An alternative approach is to call `((Main) getOwner)`

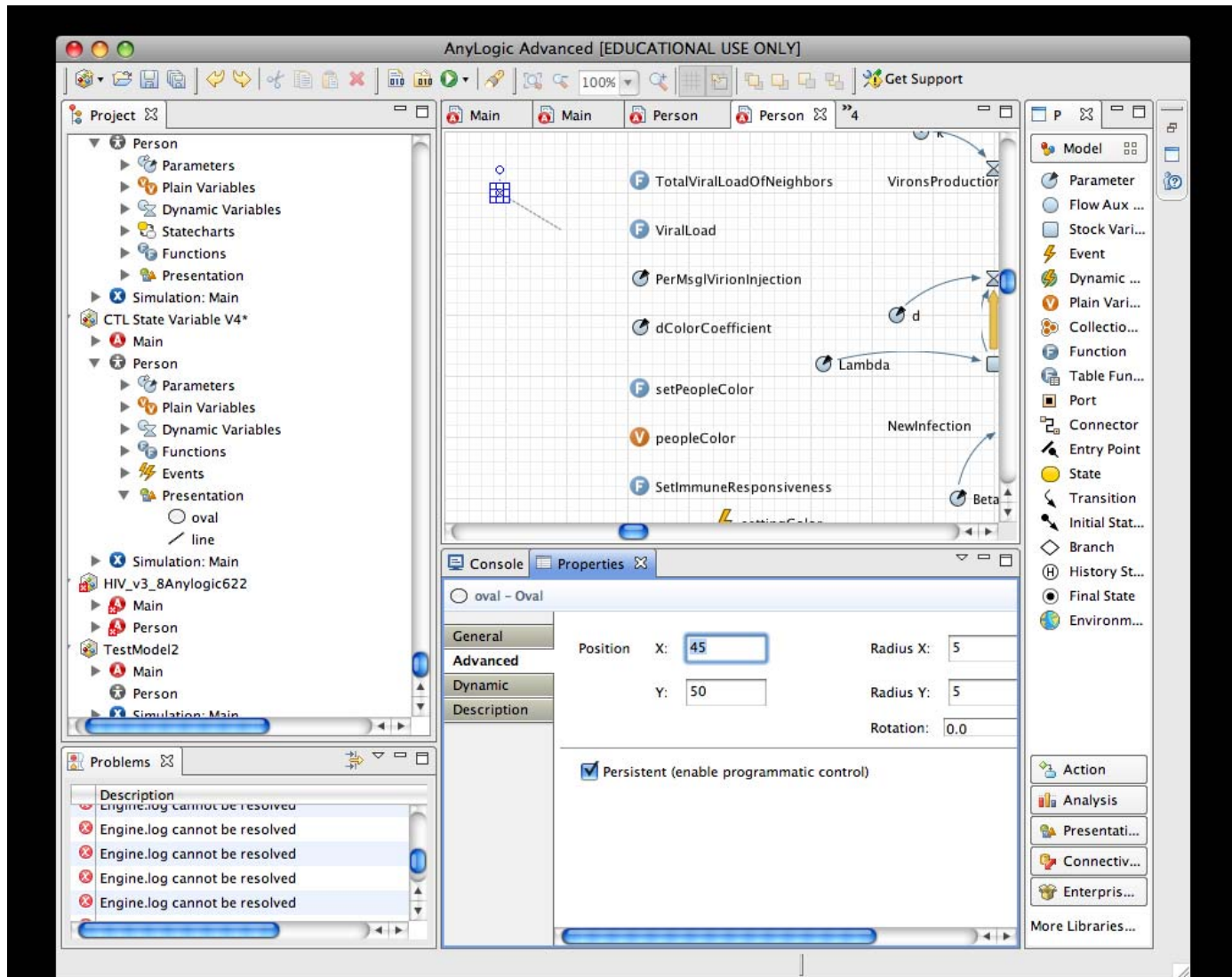
Useful Bits of Java Code

- `get_Main()` gets reference to Main object
- `ActiveObject.trace(str)` outputs string to log
- `Engine.getTime()` gets the current time
- `agents.size()` gets number of objects in collection
`agents`
- `agents.item(i)` gets item i from agent collection
- `uniform()` generates a random number from 0..1

Presentation Properties

- Both key customizable classes (“Main”, various Agent classes) can be associated with “Presentation” elements
- These elements are assembled during execution into animations & presentations of the agents
- Many of these presentation elements have properties that can be set to Java expressions

Enabling Programmatic Control



Example of Dynamic Expressions for an Agent's Presentation Properties

